# AdaBoost

#### CS109A Introduction to Data Science Pavlos Protopapas, Natesh Pillai



•Do we recombine our residual predictions at the end of the boosting process to come up with a final model prediction or do we iteratively combine residual predictions to determine the next set of residuals?

•When would gradient boosting not be suitable for an application?

•Can you combine bootstrapping and boosting?

•How do we choose the appropriate lambda parameters?

•Why does boosting face the issue of overfitting when tree number increases while on the other hand random forest doesn't face this issue?

•In boosting, how can we make sure that the different trees are not highly correlated? Is there a mechanism similar to random forest?

•In boosting, if one has extreme outliers, can it ruin the boosting model since it is trained on residuals?





# Random forest ensembles:





Using the language of gradient descent also allows us to connect gradient boosting for regression to a boosting algorithm often used for classification, AdaBoost.

In classification, we typically want to minimize the classification error:

$$\mathsf{Error} = \frac{1}{N} \sum_{n=1}^{N} \mathbb{1}(y_n \neq \hat{y}_n), \quad \mathbb{1}(y_n \neq \hat{y}_n) = \begin{cases} 0, & y_n = \hat{y}_n \\ 1, & y_n \neq \hat{y}_n \end{cases}$$

Naively, we can try to minimize Error via gradient descent, just like we did for MSE in gradient boosting.

Unfortunately, Error is not differentiable 🛞



**Our solution:** we replace the Error function with a differentiable function that is a good indicator of classification error.

The function we choose is called **exponential loss**:

ExpLoss = 
$$\frac{1}{N} \sum_{n=1}^{N} \exp(-y_n \hat{y}_n), \quad y_n \in \{-1, 1\}$$

Exponential loss is differentiable with respect to  $\hat{y}_n$  and it is an upper bound of Error.



We first compute the gradient for ExpLoss:

$$\nabla_{\hat{y}} \operatorname{Exp} = \left[-y_1 \exp\left(-y_1 \hat{y}_1\right), \dots, -y_N \exp\left(-y_N \hat{y}_N\right)\right]$$

It's easier to decompose each  $y_n \exp(-y_n \hat{y}_n)$  as  $w_n y_n$ , where  $w_n = \exp(-y_n \hat{y}_n)$ .

This way, we see that the gradient is just a re-weighting applied the target values

$$\nabla_{\hat{y}} \operatorname{Exp} = [-w_1 y_1, \dots, -w_N y_N]$$

Notice that when  $y_n = \hat{y}_n$ , the weight  $w_n$  is small; when  $y_n \neq \hat{y}_n$ , the weight is larger.



The update step in the gradient descent is

$$\hat{y}_n \leftarrow \hat{y}_n + \lambda w_n y_n, \qquad n = 1, \dots, N$$

Just like in gradient boosting, we approximate the gradient,  $\lambda w_n y_n$  with a simple model,  $T^{(i)}$ , that depends on  $x_n$ .

This means training T<sup>(i)</sup> on a re-weighted set of target values,

$$\{(x_1, w_1y_1), \dots, (x_N, w_Ny_N)\}$$

That is, gradient descent with exponential loss means iteratively training simple models that **focuses on the points misclassified by the previous model.** 



With a minor adjustment to the exponential loss function, we have the algorithm for gradient descent:

- 1. Choose an initial distribution over the training data,  $w_n = 1/N$ .
- 2. At the *i*<sup>th</sup> step, fit a simple classifier  $T^{(i)}$  on weighted training data  $\{(x_1, w_1y_1), \dots, (x_N, w_Ny_N)\}$
- 3. Update the weights:

$$w_n \leftarrow \frac{w_n \exp(-\lambda^{(i)} y_n T^{(i)}(x_n))}{Z}$$

where Z is the normalizing constant for the collection of updated weights

4. Update  $T: T \leftarrow T + \lambda^{(i)}T^{(i)}$ 

where  $\lambda$  is the learning rate.



# AdaBoost: start with equal weights





## AdaBoost: fit a simple decision tree

## fit a simple classifier $T^{(i)}$





## AdaBoost: update the weights

Update the weights: 
$$w_n \leftarrow \frac{w_n \exp(-\lambda^{(i)} y_n T^{(i)}(x_n))}{Z}$$





#### fit another simple decision tree on re-weighted data





add the new model to the ensemble:  $T \leftarrow T + \lambda^{(i)}T^{(i)}$ 





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Unlike in the case of gradient boosting for regression, we can analytically solve for the optimal learning rate for AdaBoost, by optimizing:

$$\underset{\lambda}{\operatorname{argmin}} \frac{1}{N} \sum_{n=1}^{N} \exp\left[-y_n(T+\lambda^{(i)}T^{(i)}(x_n))\right]$$

Doing so, we get that

$$\lambda^{(i)} = \frac{1}{2} \ln \frac{1 - \epsilon^{(i)}}{\epsilon^{(i)}} \quad \epsilon = \sum_{n=1}^{N} w_n \mathbb{I}\left(y_n \neq T^{(i)}\left(x_n\right)\right)$$



There are few implementations on boosting:

- XGBoost: An efficient Gradient Boosting Decision
- LGBM: Light Gradient Boosted Machines. It is a library for training GBMs developed by Microsoft, and it competes with XGBoost
- CatBoost: A new library for Gradient Boosting Decision Trees, offering appropriate handling of categorical features



# Final thoughts on Boosting

Increasing the number of trees can lead to overfitting.

Question: Why?







# Boosting Classification

The aim of this exercise to understand classification using boosting by plotting the decision boundary after each stump. Your plot may resemble the image below:







