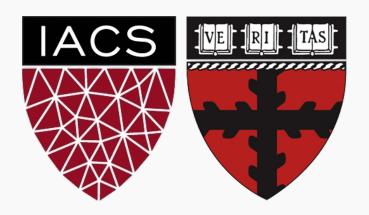
Optimizers

CS109A Introduction to Data Science Pavlos Protopapas, Kevin Rader and Chris Tanner



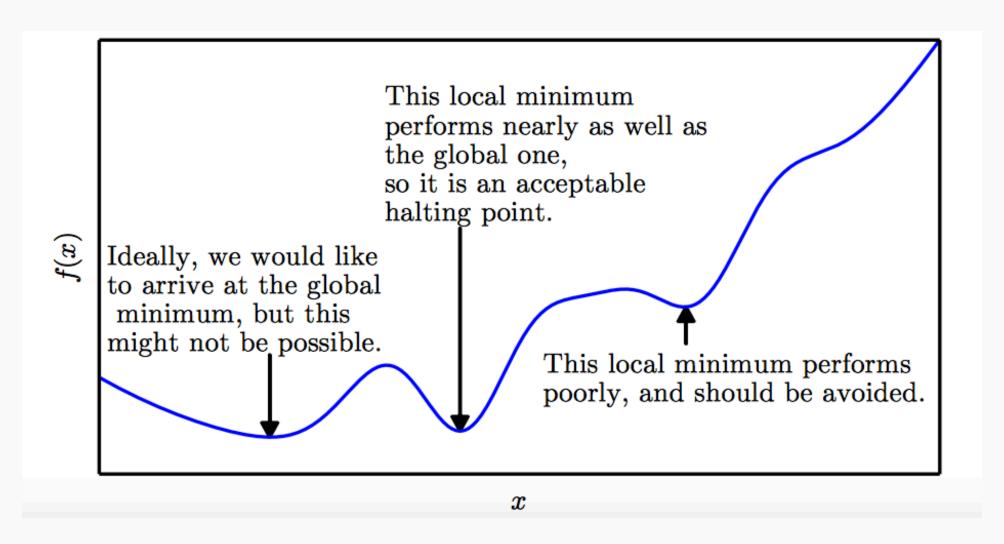
Outline

Optimization

- Challenges in Optimization
- Momentum
- Adaptive Learning Rate



Local Minima





Local Minima

Old view: local minima is major problem in neural network training

Recent view:

- For sufficiently large neural networks, most local minima incur low cost
- Not important to find true global minimum

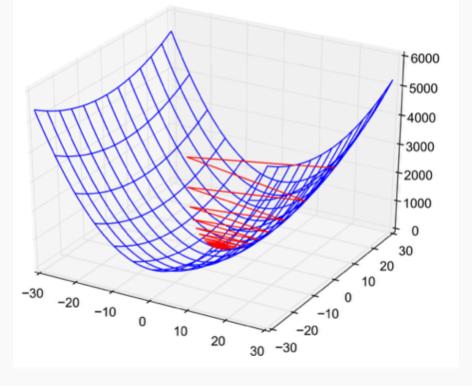


Poor Conditioning

Poorly conditioned Hessian matrix

High curvature: small steps leads to huge increase
 Learning is slow despite strong gradients

Oscillations slow down progress

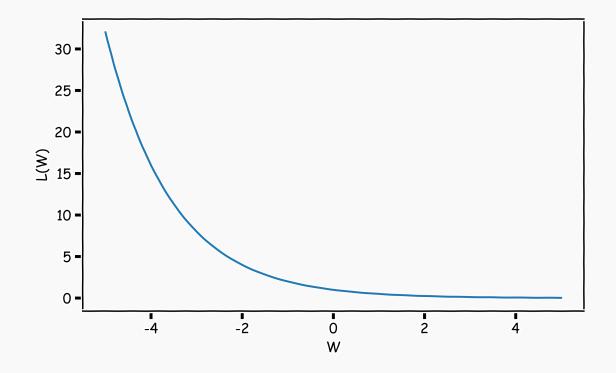




No Critical Points

Some cost functions do not have critical points. In particular classification.

WHY?





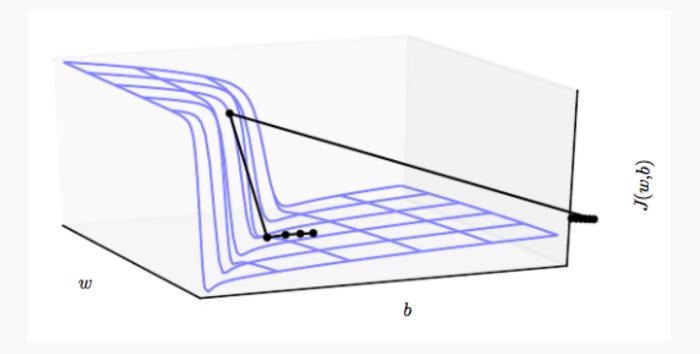
Exploding and Vanishing Gradients

Exploding gradients lead to cliffs

Can be mitigated using gradient clipping

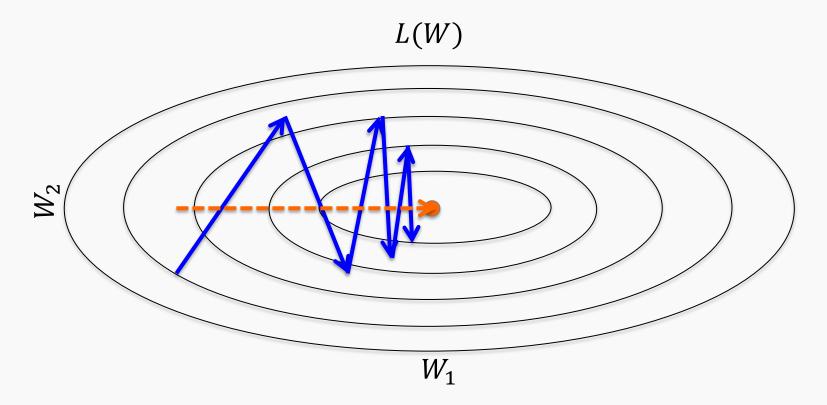
if
$$||g|| > u$$

$$g \leftarrow \frac{gu}{\|g\|}$$





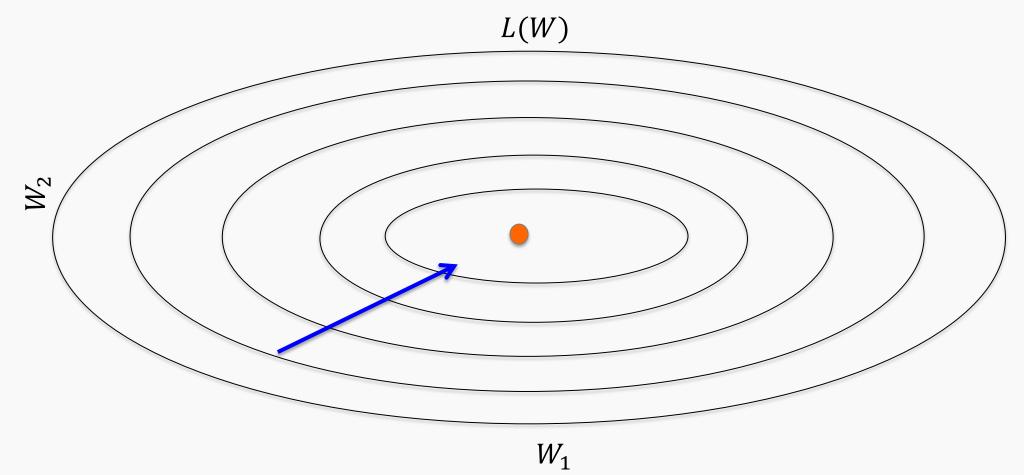
Oscillations because updates do not exploit curvature information



Average gradient presents faster path to optimal: vertical components cancel out



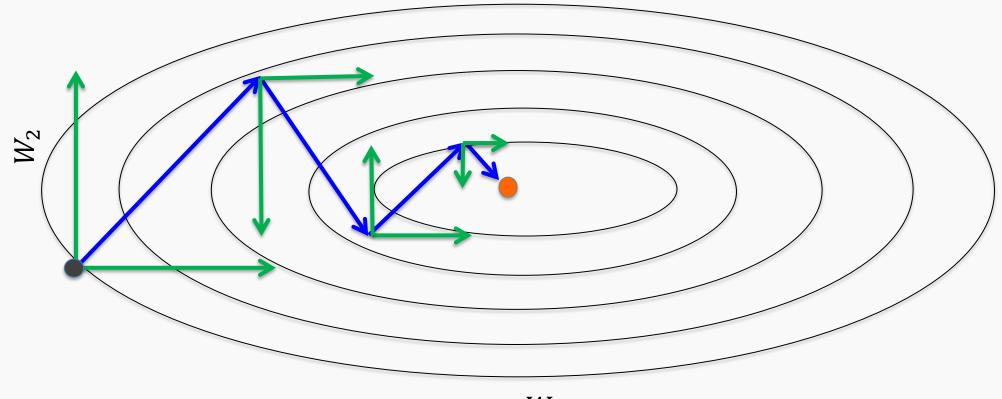
Question: Why not this?





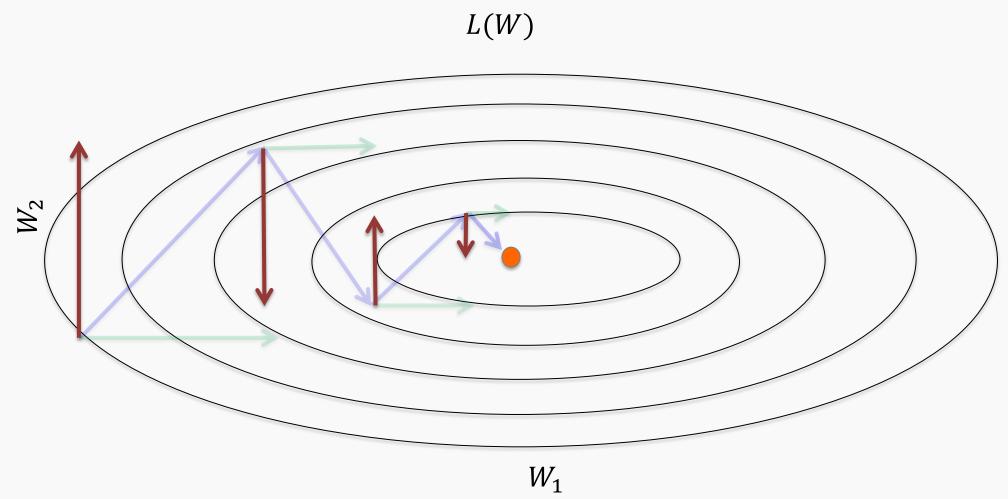
Let us figure out an algorithm which will lead us to the minimum faster.

L(W)

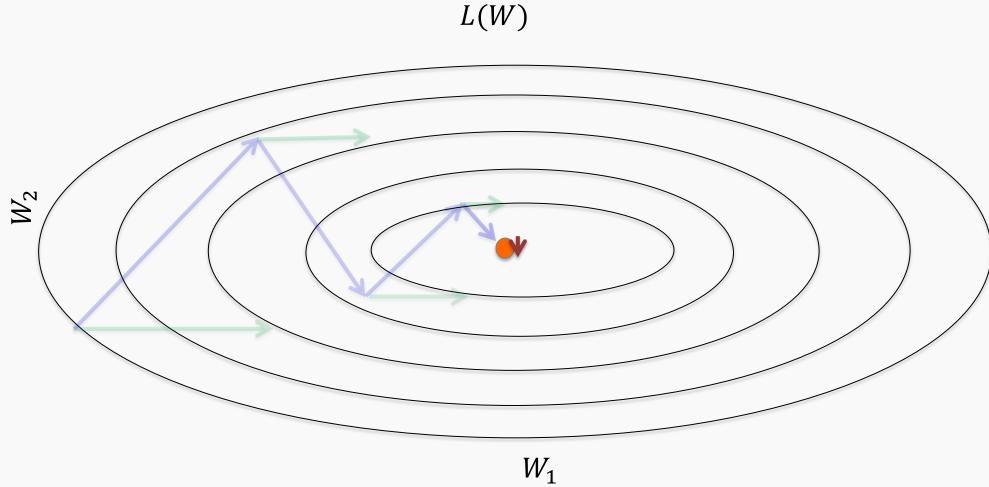




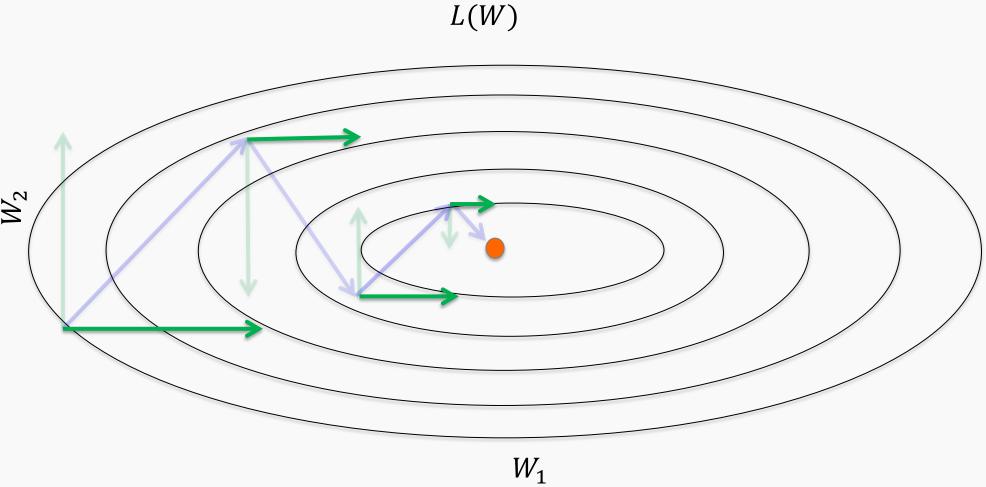
Look each component at a time



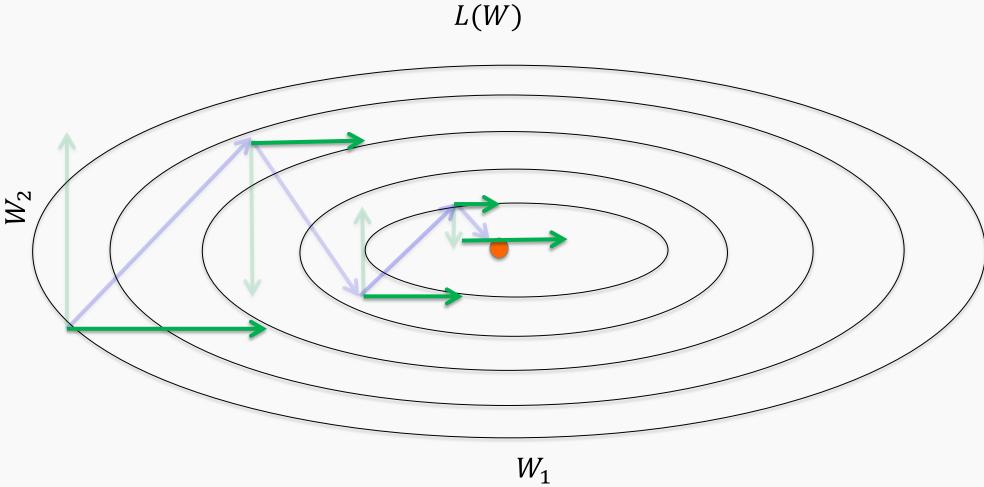




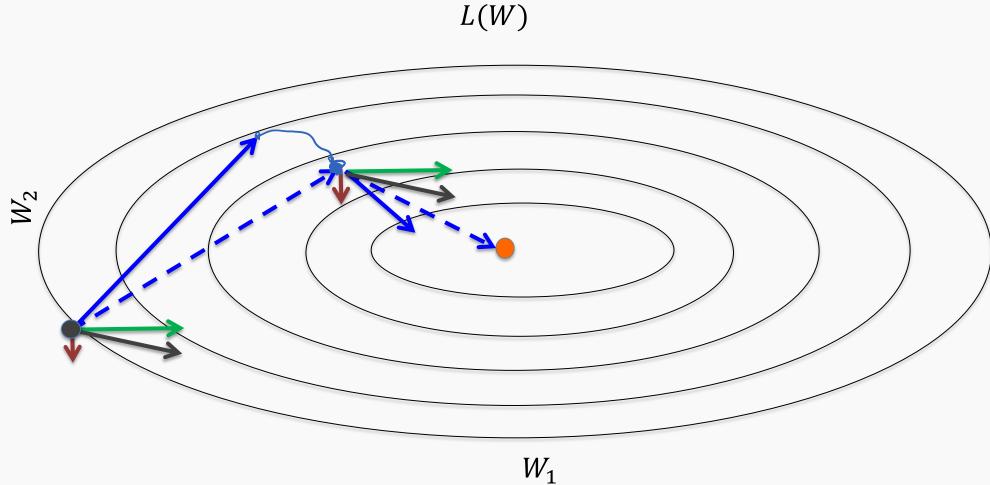














Old gradient descent:

$$g = \frac{1}{m} \sum_{i} \nabla_{W} L(f(x_i; W), y_i)$$

$$W^* = W - \eta g$$

New gradient descent with momentum:

$$\nu = \alpha \nu + (1 - \alpha) g$$

$$W^* = W - \eta v$$



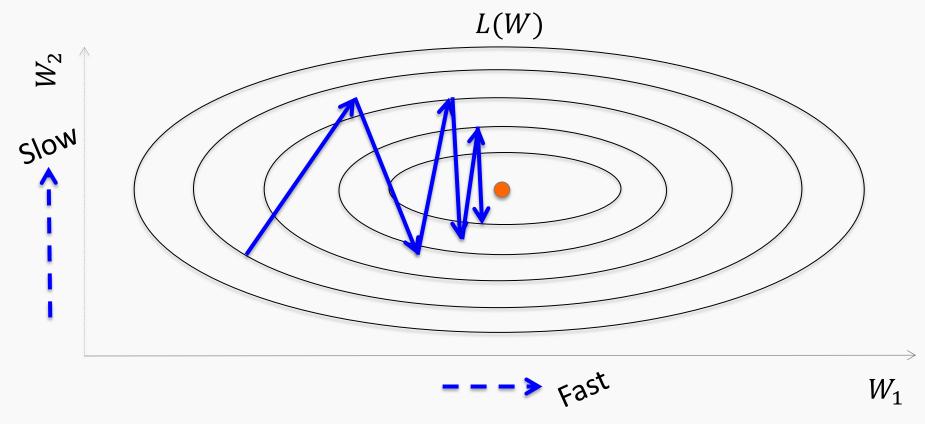
 $\alpha \in [0,1)$ controls how quickly effect of past gradients decay

Outline

Optimization

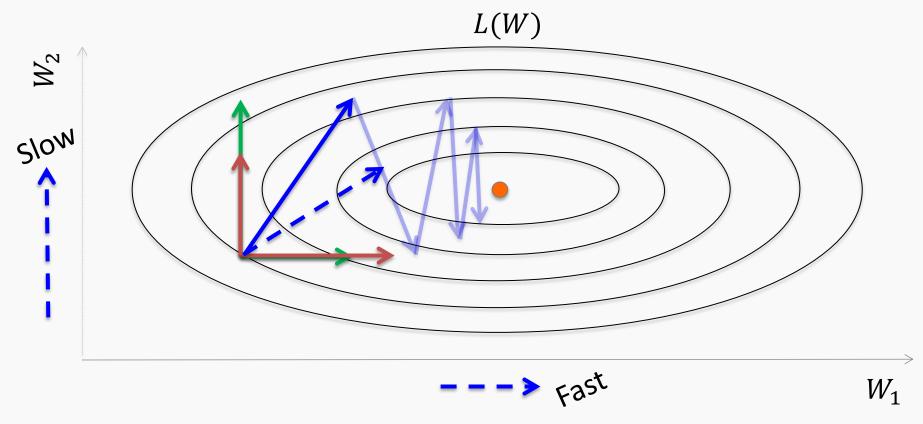
- Challenges in Optimization
- Momentum
- Adaptive Learning Rate





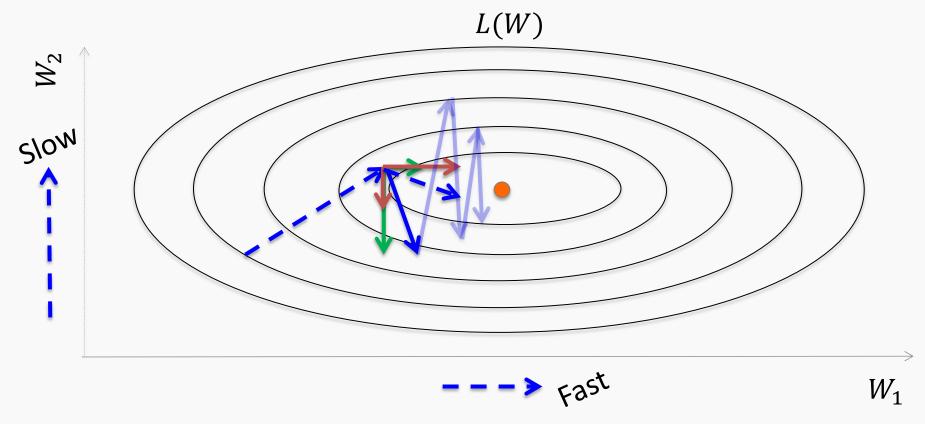
Oscillations along vertical direction





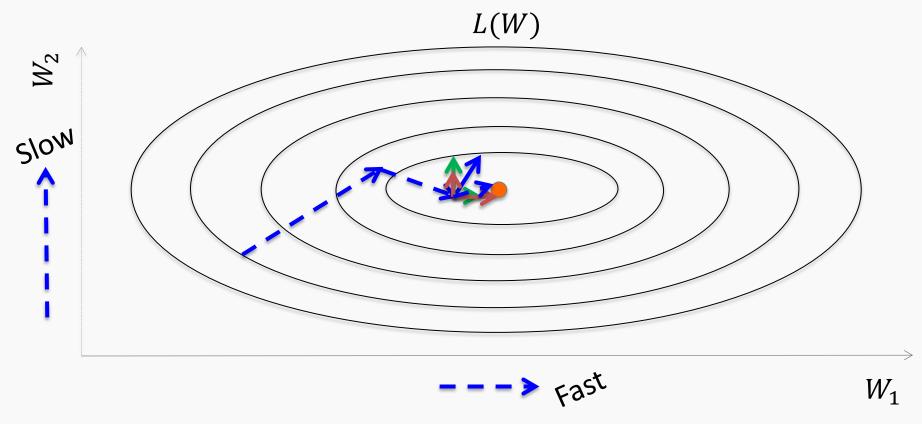
Oscillations along vertical direction





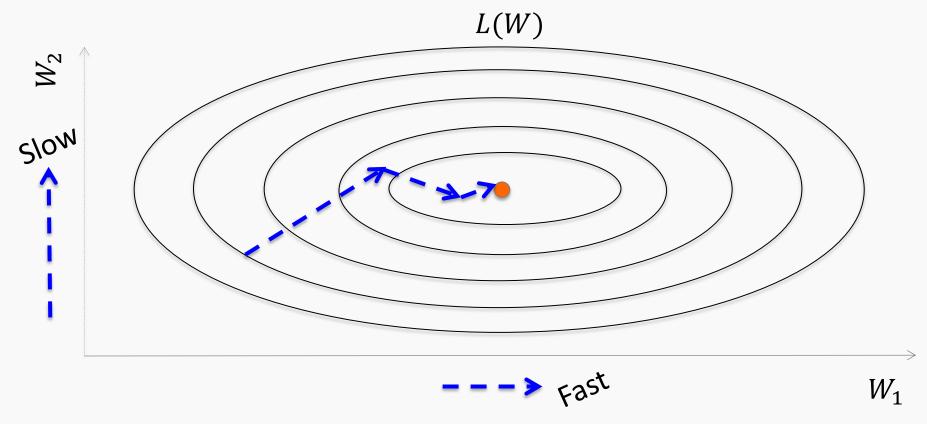
Oscillations along vertical direction





Oscillations along vertical direction





Oscillations along vertical direction



AdaGrad

Accumulate squared gradients:

$$r_i = r_i + g_i^2$$

g is the gradient

• Update each parameter:

$$W_i = W_i - rac{\epsilon}{\delta + \sqrt{r_i}} g_i$$

Greater progress along gently sloped directions

Inversely proportional to cumulative gradient



AdaGrad

 δ is a small number, making sure this does not become too large

Old gradient descent:

$$g = \frac{1}{m} \sum_{i} \nabla_{W} L(f(x_i; W), y_i) \qquad W^*$$

We would like $\lambda' s$ not to be the same and inversely proportiona the $|g_i|$

$$W_i^* = W_i - \eta_i g_i \qquad \qquad \eta_i \propto \frac{1}{|g_i|} = \frac{1}{\delta + |g_i|}$$

New gradient descent with adaptive learning rate:

$$r_i^* = r_i + g_i^2 \qquad \qquad W_i^* = W_i - \frac{\epsilon}{\delta + \sqrt{r_i}} g_i$$



RMSProp

- For non-convex problems, AdaGrad can prematurely decrease learning rate
- Use exponentially weighted average for gradient accumulation

$$r_i = \rho r_i + (1 - \rho)g_i^2$$

$$W_i = W_i - \frac{\epsilon}{\delta + \sqrt{r_i}} g_i$$



Adam

- RMSProp + Momentum
- Estimate first moment:

$$v_i = \rho_1 v_i + (1 - \rho_1) g_i$$

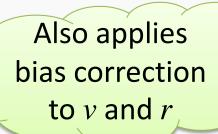
Estimate second moment:

$$r_i = \rho_2 r_i + (1 - \rho_2) g_i^2$$

Update parameters:

$$W_i = W_i - \frac{\epsilon}{\delta + \sqrt{r_i}} \nu_i$$

Works well in practice, it is fairly robust to hyper-parameters





Bias Correction

To performe bias correction on the two running average variables - ν and r use the following equations. Do this before they are used to update the weight.

- $\nu_{biascorr} = \nu/(1-\rho_1^t)$
- $ullet r_{biascorr} = r/(1ho_2^t)$

where t is the number of the current iteration.





Momentum Weighting Parameter



