# Gradient Boosting

#### CS109A Introduction to Data Science Pavlos Protopapas, Kevin Rader and Chris Tanner



#### **Comparison of Models:**

Choosing the right model isn't just about minimizing the test errors. We want extra insights from our models:

	ltas a fixed form f(x) parametric	easy to inlerpret	computationa complexity
Linear Regression	YES	YES	LOW
Polynomial Regression	YES	NO	LOW
Regression Trees	0%	YES	LGW
Bagging and RF	NO	465/NG	Medina
K-nearest Neighbors	NO	YES	нісн



#### "Can a set of weak learners create a single strong learner?" Leslie Gabriel Valiant

How many jelly beans do you see?









**Question:** Could we address the shortcomings of single decision trees models in some other way?

For example, rather than performing variance reduction on complex trees, can we decrease the bias of simple trees - make them more expressive?

Can we learn from our mistakes?

A solution to this problem, making an expressive model from simple trees, is another class of ensemble methods called **boosting**.



The key intuition behind boosting is that one can take an ensemble of simple models  $\{T_h\}_{h\in H}$  and additively combine them into a single, more complex model.

Each model *T<sub>h</sub>* might be a poor fit for the data, but a linear combination of the ensemble:

$$T = \sum_{h} \lambda_{h} T_{H}$$

can be expressive/flexible.

**Question:** But which models should we include in our ensemble? What should the coefficients or weights in the linear combination be?



**Gradient boosting** is a method for iteratively building a complex regression model *T* by adding simple models.

Each new simple model added to the ensemble compensates for the weaknesses of the current ensemble.



```
1. Fit a simple model T^{(0)} on the training data
                                 \{(x_1, y_1), \dots, (x_N, y_N)\}
    Set T \leftarrow T^{(0)}.
    Compute the residuals \{r_1, \ldots, r_N\} for T.
2. Fit a simple model, T^{(1)}, to the current residuals, i.e. train using
                                  \{(x_1, r_1), \dots, (x_N, r_N)\}
3. Set T \leftarrow T + \lambda T^{(1)}
4. Compute residuals, set r_n \leftarrow r_n - \lambda T^i(x_n), n = 1, ..., N
5. Repeat steps 2-4 until stopping condition met.
    where \lambda is a constant called the learning rate.
```







Fit a simple model  $T^{(0)}$ 





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Compute the residuals  $\{r_1, \ldots, r_N\}$  for T.





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train usin:  $\{(x_1, r_1), ..., (x_N, r_N)\}$ 



Set 
$$T \leftarrow T + \lambda T^{(1)}$$





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$$r_n \leftarrow r_n - \lambda T^i(x_n)$$





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Intuitively, each simple model  $T^{(i)}$  we add to our ensemble model T, models the errors of T.

Thus, with each addition of  $T^{(i)}$ , the residual is reduced

$$r_n - \lambda T^{(i)}(x_n)$$

Note that gradient boosting has a tuning parameter,  $\lambda$ .

If we want to easily reason about how to choose  $\lambda$  and investigate the effect of  $\lambda$  on the model *T*, we need a bit more mathematical formalism. In particular, how can we effectively descend through this optimization via an iterative algorithm?

We need to formulate gradient boosting as a type of *gradient descent*.



#### Gradient Boosting as Gradient Descent

Often in regression, our objective is to minimize the MSE

$$\mathsf{MSE}(\hat{y}_1, \dots, \hat{y}_N) = \frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2$$

Treating this as an optimization problem, we can try to directly minimize the MSE with respect to the predictions

$$\nabla \mathsf{MSE} = \begin{bmatrix} \frac{\partial \mathsf{MSE}}{\partial \hat{y}_1}, \dots, \frac{\partial \mathsf{MSE}}{\partial \hat{y}_N} \end{bmatrix}$$
$$= -2 \left[ y_1 - \hat{y}_1, \dots, y_N - \hat{y}_N \right]$$
$$= -2 \left[ r_1, \dots, r_N \right]$$

The update step for gradient descent would look like

$$\hat{y}_n \leftarrow \hat{y}_n + \lambda r_n, \quad n = 1, \dots, N$$



There are two reasons why minimizing the MSE with respect to  $\hat{y}_n$ 's is not interesting:

- We know where the minimum MSE occurs:  $\hat{y}_n = y_n$ , for every *n*.
- Learning sequences of predictions, ŷ<sub>n</sub><sup>1</sup>, ..., ŷ<sub>n</sub><sup>i</sup>, ..., does not produce a model. The predictions in the sequences do not depend on the predictors!





The solution is to change the update step in gradient descent. Instead of using the gradient - the residuals - we use an **approximation** of the gradient that depends on the predictors:

$$\hat{y} \leftarrow \hat{y}_n + \lambda \, \hat{r}_n(x_n), \qquad n = 1, \dots, N$$

In gradient boosting, we use a simple model to approximate the residuals,  $\hat{r}_n(x_n)$ , in each iteration.

**Motto:** gradient boosting is a form of gradient descent with the MSE as the loss (objective) function.

**Technical note:** note that gradient boosting is descending in a space of models or functions relating  $x_n$  to  $y_n$ !



## Gradient Boosting as Gradient Descent (cont.)

But why do we care that gradient boosting is gradient descent?

By making this connection, we can import the massive amount of techniques for studying gradient descent to analyze gradient boosting.

For example, we can easily reason about how to choose the learning rate  $\lambda$  in gradient boosting.



Under ideal conditions, gradient descent iteratively approximates and converges to the optimum.

#### When do we terminate gradient descent?

- We can limit the number of iterations in the descent. But for an arbitrary choice of maximum iterations, we cannot guarantee that we are sufficiently close to the optimum in the end.
- If the descent is stopped when the updates are sufficiently small (e.g. the residuals of T are small), we encounter a new problem: the algorithm may never terminate!

Both problems have to do with the magnitude of the learning rate,  $\lambda$ .



For a constant learning rate,  $\lambda$ , if  $\lambda$  is too small, it takes too many iterations to reach the optimum.



If  $\lambda$  is too large, the algorithm may 'bounce' around the optimum and never get sufficiently close.





# Today's lucky student: Anyone awake! Exercise goal Regression with Boosting



