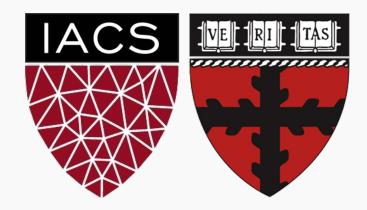
## Lecture 5: Linear Regression

## CS109A Introduction to Data Science Pavlos Protopapas, Kevin Rader and Chris Tanner



# ANNOUNCEMENTS

• Advanced Sections (A-Sections):

TODAY @ **4:30pm** (MD G115)

Linear Algebra and Hypothesis Testing, Pavlos + Kevin

### • ED-Exercises grading:

- All exercises together are equivalent to one question for that day's quiz.
- We grade for accuracy. You will receive full grade even if it fails the finicky test.
- We will grade these exercises very leniently.



## Summary from last lecture

# When you're a kNN with k = 2





**Model Fitness** 

How does the model perform predicting?

**Comparison of Two Models** 

How do we choose from two different models?

**Evaluating Significance of Predictors** 

Does the outcome depend on the predictors?

How well do we know  $\widehat{f}$ 

The confidence intervals of our  $\hat{f}$ 

– This lecture



- Linear models
- Estimate of the regression coefficients
  - Brute Force
  - Exact method
  - Gradient Descent
- Confidence intervals for the predictors estimates
- Bootstrap
- Evaluating significance of predictors
- How well we know the model  $\hat{f}$



## Lecture Outline

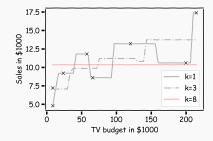
#### • Linear models

- Estimate of the regression coefficients
  - Brute Force
  - Exact method
  - Gradient Descent
- Confidence intervals for the predictors estimates
- Bootstrap
- Evaluating significance of predictors
- How well we know the model  $\hat{f}$



Note that in building our kNN model for prediction, we did not compute a closed form for  $\hat{f}$ .

What if we ask the question:



"how much more sales do we expect if we double the TV advertising budget?"

Alternatively, we can build a model by first assuming a simple form of f:

$$Y = f(X) + \epsilon = \beta_1 X + \beta_0 + \epsilon.$$



... then it follows that our estimate is:

$$\widehat{Y} = \widehat{f}(X) = \widehat{\beta_1}X + \widehat{\beta_0}$$

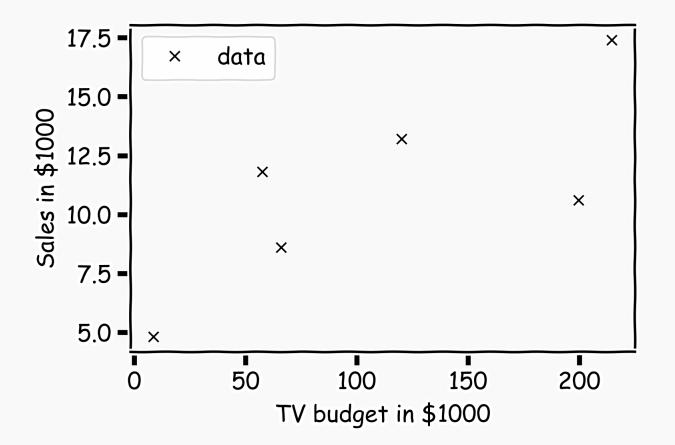
where  $\hat{\beta}_1$  and  $\hat{\beta}_0$  are **estimates** of  $\beta_1$  and  $\beta_0$  respectively, that we compute using observations.



- Linear models
- Estimate of the regression coefficients
  - Brute Force
  - Exact method
  - Gradient Descent
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- Bootstrap
- Evaluating significance of predictors
- How well we know the model  $\hat{f}$

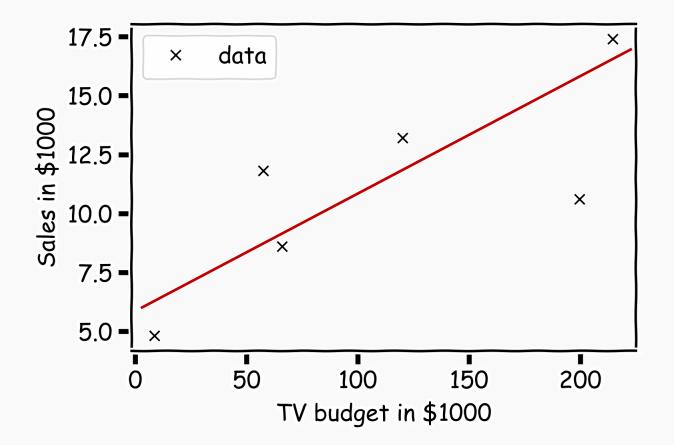


For a given data set



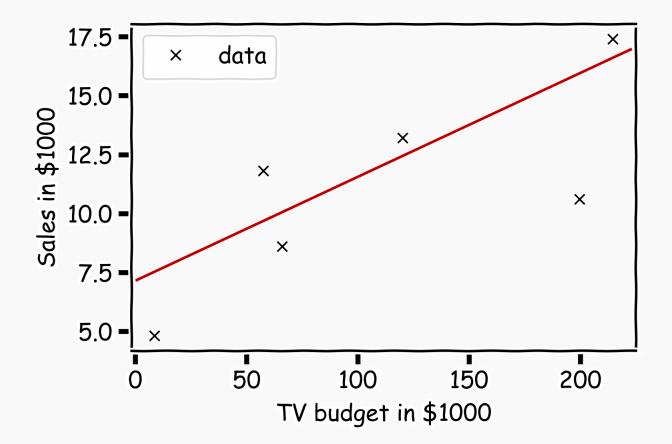


Is this line good?



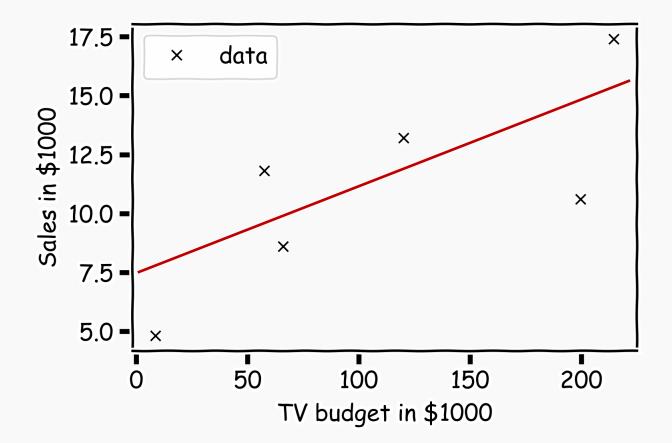


Maybe this one?



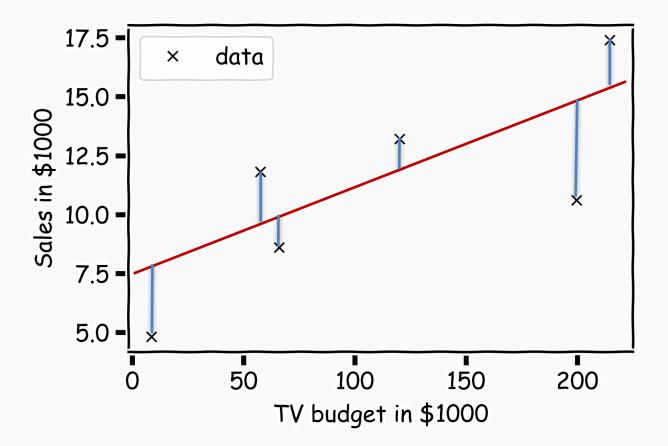


Or this one?





**Question:** Which line is the best? First calculate the residuals





Again we use MSE as our **loss function**,

$$L(\beta_0, \beta_1) = \frac{1}{n} \sum_{i=1}^n (y_i - \widehat{y}_i)^2 = \frac{1}{n} \sum_{i=1}^n [y_i - (\beta_1 X + \beta_0)]^2.$$

We choose  $\hat{\beta}_1$  and  $\hat{\beta}_0$  in order to minimize the predictive errors made by our model, i.e. minimize our loss function.

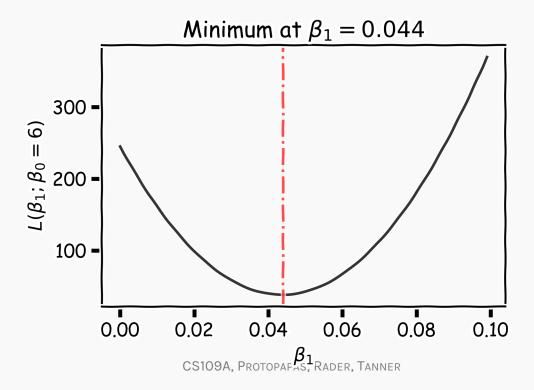
Then the optimal values for  $\hat{\beta}_0$  and  $\hat{\beta}_1$  should be:

$$\widehat{\beta}_0, \widehat{\beta}_1 = \underset{\beta_0, \beta_1}{\operatorname{argmin}} L(\beta_0, \beta_1).$$



A way to estimate  $\operatorname{argmin}_{\beta_0,\beta_1} L$  is to calculate the loss function for every possible  $\beta_0$  and  $\beta_1$ . Then select the  $\beta_0$  and  $\beta_1$  where the loss function is minimum.

E.g. the loss function for different  $\beta_1$  when  $\beta_0$  is fixed to be 6:





Take the partial derivatives of *L* with respect to  $\beta_0$  and  $\beta_1$ , set to zero, and find the solution to that equation. This procedure will give us explicit formulae for  $\hat{\beta}_0$  and  $\hat{\beta}_1$ :

$$\hat{\beta}_1 = \frac{\sum_i (x_i - \overline{x})(y_i - \overline{y})}{\sum_i (x_i - \overline{x})^2}$$
$$\hat{\beta}_0 = \overline{y} - \hat{\beta}_1 \overline{x}$$

where  $\bar{y}$  and  $\bar{x}$  are sample means.

The line:

$$\widehat{Y} = \widehat{\beta}_1 X + \widehat{\beta}_0$$

is called the **regression line**.



$$L(\beta_0, \beta_1) = \frac{1}{n} \sum_{i} \left[ y_i - (\beta_0 - \beta_1 x_i) \right]^2$$

$$\frac{dL(\beta_0, \beta_1)}{d\beta_0} = 0$$
  

$$\Rightarrow \frac{2}{n} \sum_i (y_i - \beta_0 - \beta_1 x_i) = 0$$
  

$$\Rightarrow \frac{1}{n} \sum_i y_i - \beta_0 - \beta_1 \frac{1}{n} \sum_i x_i = 0$$
  

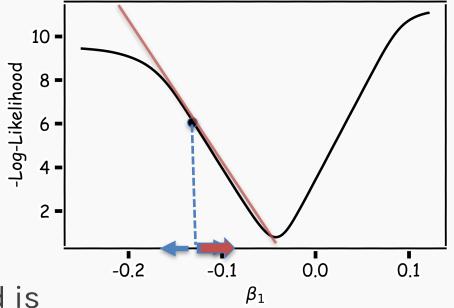
$$\Rightarrow \beta_0 = \bar{y} - \beta_1 \bar{x}$$

$$\begin{aligned} \frac{dL(\beta_0, \beta_1)}{d\beta_1} &= 0 \\ \Rightarrow \frac{2}{n} \sum_i (y_i - \beta_0 - \beta_1 x_i)(-x_i) &= 0 \\ \Rightarrow -\sum_i x_i y_i + \beta_0 \sum_i x_i + \beta_1 \sum_i x_i^2 &= 0 \\ \Rightarrow -\sum_i x_i y_i + (\bar{y} - \beta_1 \bar{x}) \sum_i x_i + \beta_1 \sum_i x_i^2 &= 0 \\ \Rightarrow \beta_1 \left( \sum_i x_i^2 - n\bar{x}^2 \right) &= \sum_i x_i y_i - n\bar{x}\bar{y} \\ \Rightarrow \beta_1 &= \frac{\sum_i x_i y_i - n\bar{x}\bar{y}}{\sum_i x_i^2 - n\bar{x}^2} \\ \Rightarrow \beta_1 &= \frac{\sum_i (x_i - \bar{x})(y_i - \bar{y})}{\sum_i (x_i - \bar{x})^2} \end{aligned}$$



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## Estimate of the regression coefficients: gradient descent



A more flexible method is

- Start from a random point
  - 1. Determine which direction to go to reduce the loss (left or right)
  - 2. Compute the slope of the function at this point and step to the right if slope is negative or step to the left if slope is positive
  - 3. Goto to #1



## Estimate of the regression coefficients: gradient descent

## Question: What is the mathematical function that describes the slope? Derivative

**Question:** What do you think it is a good approach for telling the model how to change (what is the step size) to become better?

# If the step is proportional to the slope then you avoid overshooting the minimum

Question: How do we generalize this to more than one predictor? Take the derivative with respect to each coefficient and do the same sequentially



Estimate of the regression coefficients: gradient descent

We know that we want to go in the opposite direction of the derivative and we know we want to be making a step proportionally to the derivative.

Making a step means:  $w^{new} = w^{old} + step$ Deposite direction of the derivative and proportional to the derivative means:  $w^{new} = w^{old} - \lambda \frac{d\mathcal{L}}{dw}$ 

 $w = \beta_0, \beta_1$ 

Change to more conventional notation:

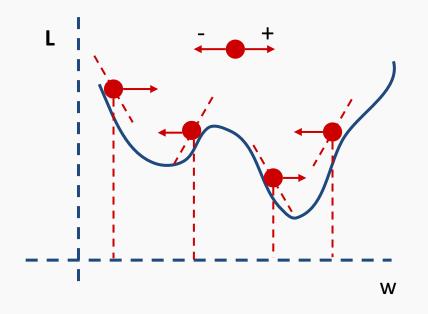
$$w^{(i+1)} = w^{(i)} - \lambda \frac{d\mathcal{L}}{dw}$$

Notation:

#### Summary of Gradient Descent

- Algorithm for optimization of first order to finding a minimum of a function.
- It is an iterative method.
- L is decreasing in the direction of the negative derivative.
- The learning rate is controlled by the magnitude of  $\lambda$ .

$$w^{(i+1)} = w^{(i)} - \lambda \frac{d\mathcal{L}}{dw}$$

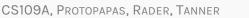


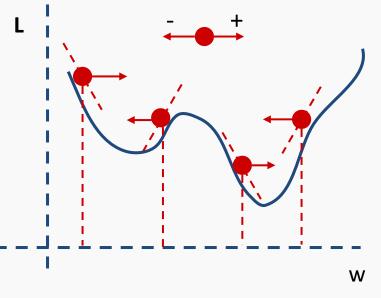


Gradient Descent Considerations (more in coming lectures)

- We still need to derive or compute the derivatives.
- We need to know what is the learning rate or how to set it.
- We need to avoid local minima.
- Finally, the full loss function includes summing up all individual 'errors'. This can be hundreds of thousands of examples.







• In linear regression, there are no local minima because the loss function is convex

• In linear regression, we often use the exact formula

• We will talk about optimization again in Neural Network lecture and the last advanced sections



- Linear models
- Estimate of the regression coefficients
  - Brute Force
  - Exact method
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**Question:** What do you think a predictor coefficient means?

Sales = 7.5 + 0.04 TV

What does 7.5 mean and what does 0.04 mean?

If we increase the TV by \$1000, what would you expect the increase in sales to be?

What if? Sales = 7.5 + 1.01 TV

The interpretation of the predictors depends on the values but decisions depend on how much we trust these values.

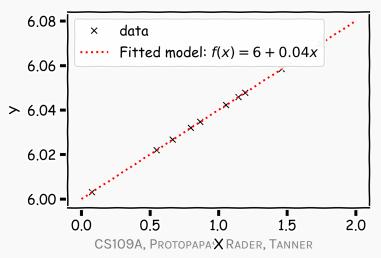


We interpret the  $\varepsilon$  term in our observation

$$y = f(x) + \epsilon$$

to be noise introduced by random variations in natural systems or imprecisions of our scientific instruments.

If we knew the exact form of f(x), for example,  $f(x) = \beta_0 + \beta_1 x$ , and there was no  $\varepsilon$ , then estimating the  $\hat{\beta}'s$  would have been exact (so is 1.01 worth it?).





**However**, three things happen, which result in mistrust of the values of  $\hat{\beta}'s$ :

- $\boldsymbol{\varepsilon}$  is always there
- we do not know the exact form of f(x)
- limited sample size

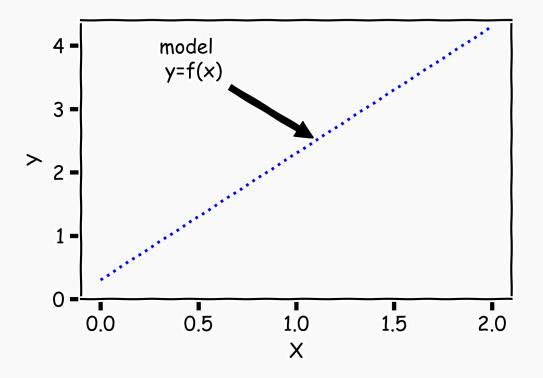
#### We will first address $\boldsymbol{\epsilon}$

We call  $\varepsilon$  the measurement error or *irreducible error*. Since even predictions made with the actual function f will not match observed values of y.

Because of  $\varepsilon$ , every time we measure the response Y for a fix value of X, we will obtain a different observation, and hence a different estimate of  $\hat{\beta}'s$ .

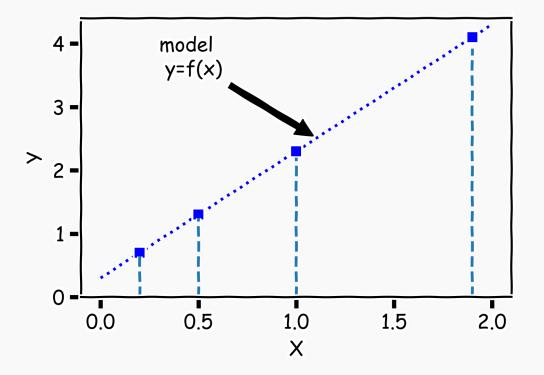


Start with a model



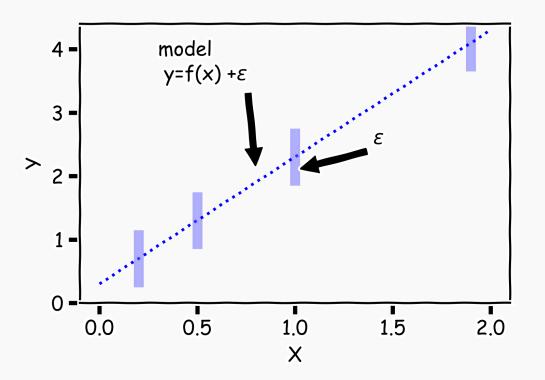


For a some values of X, Y = f(X)



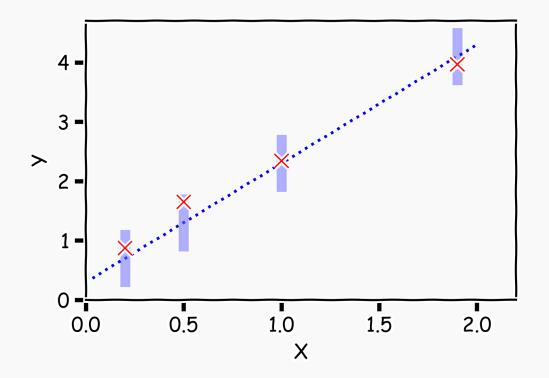


But due to error, every time we measure the response Y for a fixed value of X we will obtain a different observation.



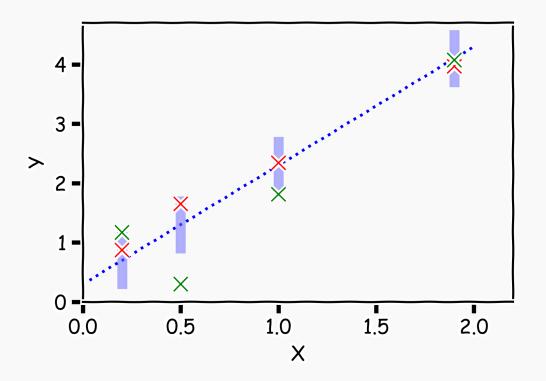


One set of observations, "one realization" we obtain one set of Ys (red crosses).



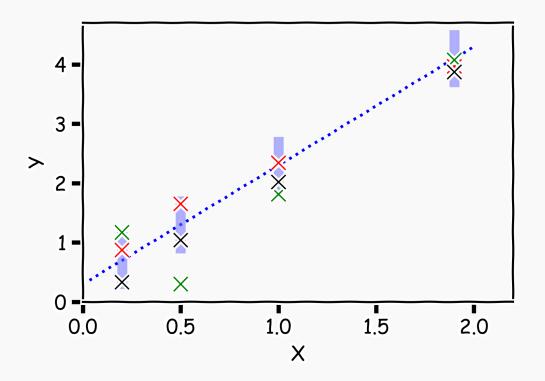


Another set of observations, "another realization" we obtain another set of Ys (green crosses).



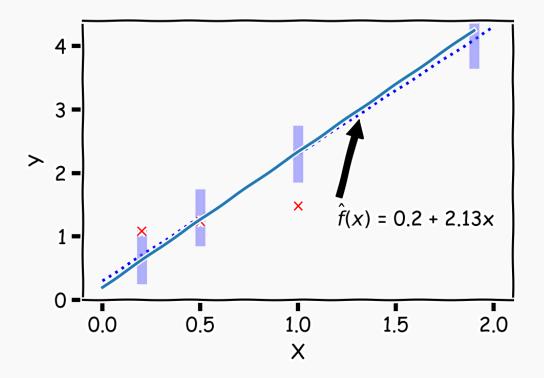


Another set of observations, "another realization" we obtain another set of Ys (black crosses).



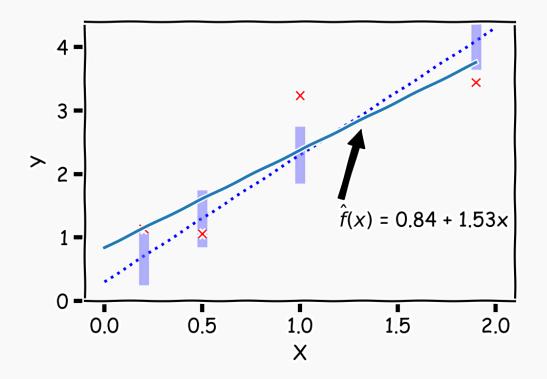


For each one of those "realizations", we could fit a model and estimate  $\hat{\beta}_0$  and  $\hat{\beta}_1.$ 



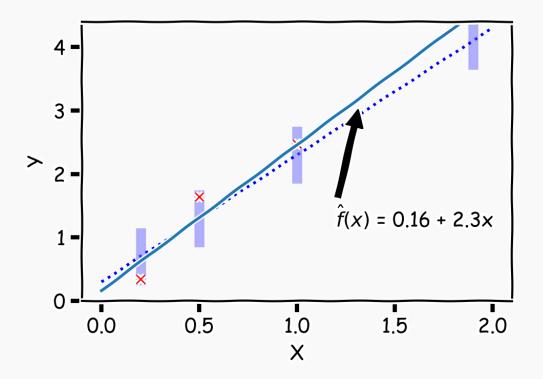


For each one of those "realizations", we could fit a model and estimate,  $\hat{\beta}_0$  and  $\hat{\beta}_1.$ 





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So if we just have one set of measurements of  $\{X, Y\}$ , our estimates of  $\hat{\beta}_0$ and  $\hat{\beta}_1$  are just for this particular realization.

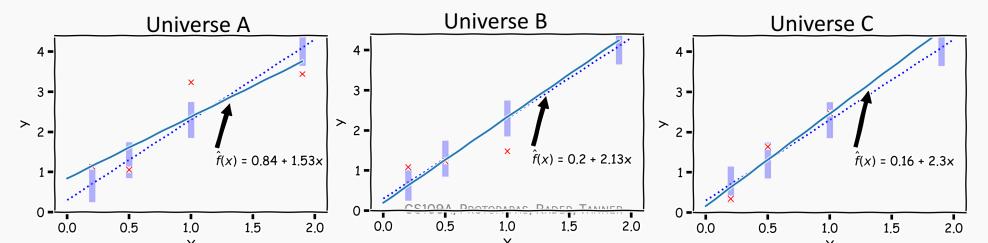




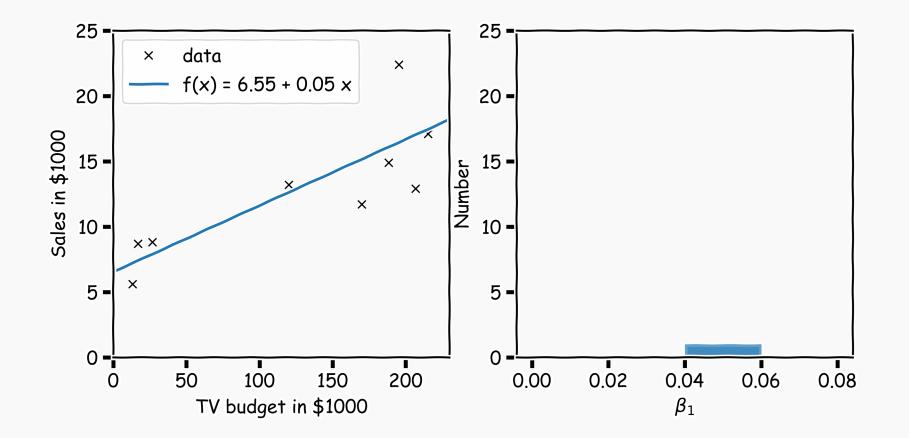
So if we just have one set of measurements of  $\{X, Y\}$ , our estimates of  $\hat{\beta}_0$  and  $\hat{\beta}_1$  are just for this particular realization.

**Question:** If this is just one realization of the reality how do we know the truth? How do we deal with this conundrum?

**Imagine** (magic realism) we have parallel universes and we repeat this experiment on each of the other universes.

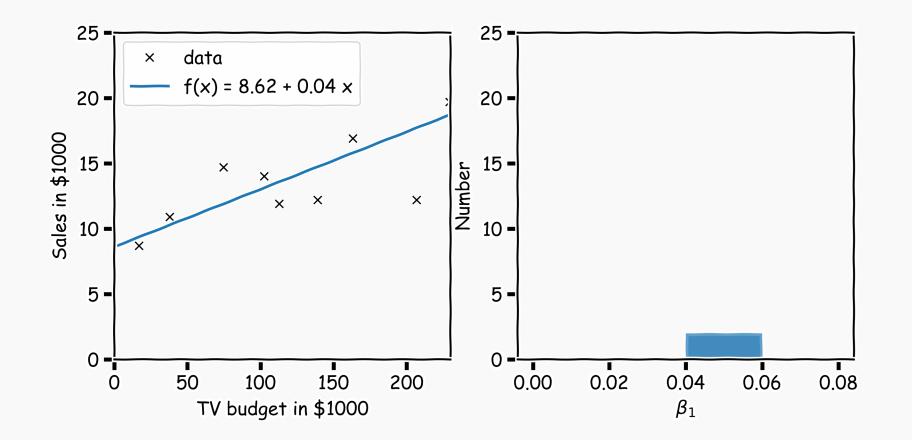


In our magical realisms, we can now sample multiple times



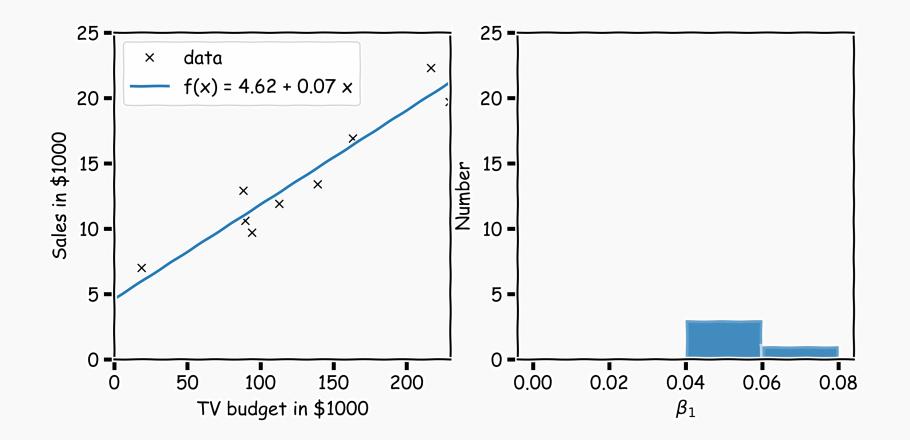


Another sample



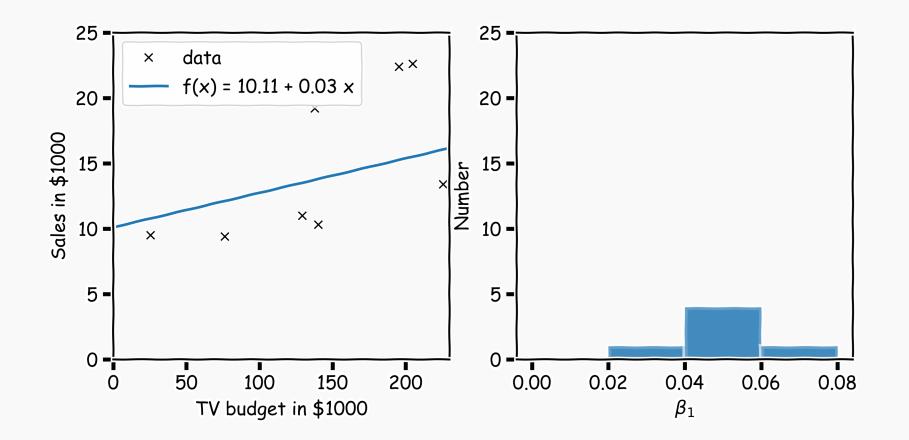


Another sample



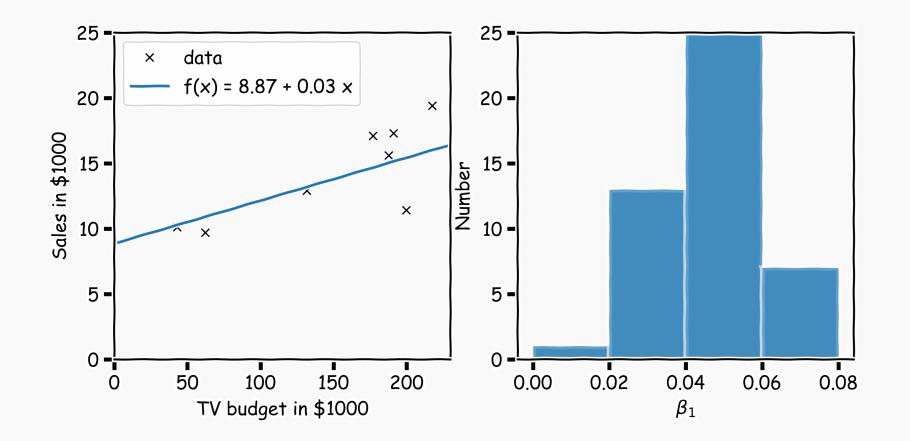


And another sample





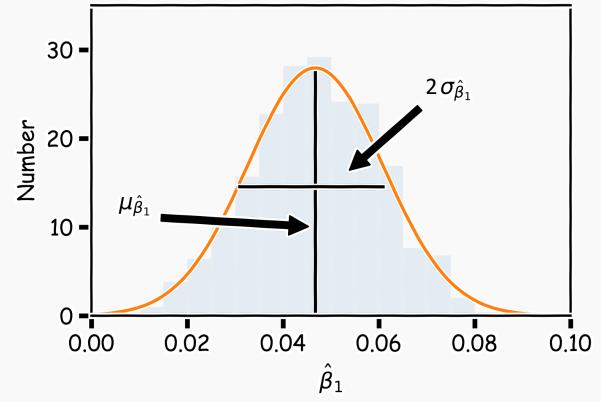
Repeat this for 100 times





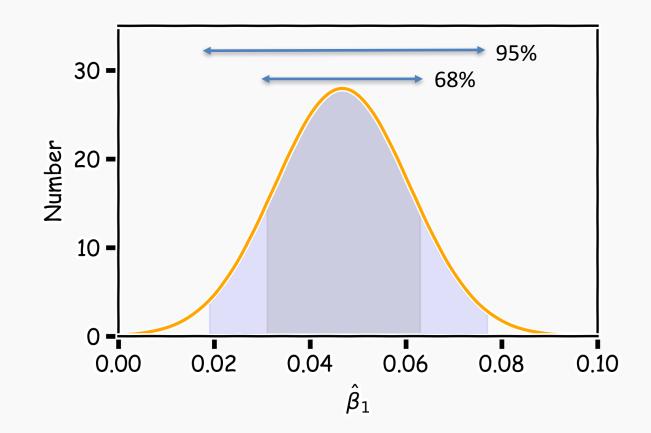
We can now estimate the mean and standard deviation of all the estimates  $\hat{\beta}_1.$ 

The variance of  $\hat{\beta}_0$  and  $\hat{\beta}_1$  are also called their **standard errors**,  $SE(\hat{\beta}_0)$ ,  $SE(\hat{\beta}_1)$ .





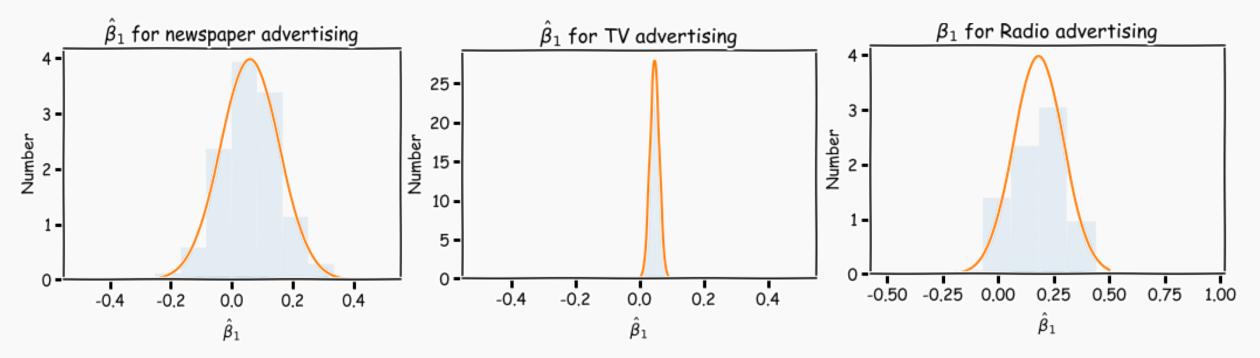
Finally we can calculate the confidence intervals, which are the ranges of values such that the **true** value of  $\beta_1$  is contained in this interval with *n* percent probability.





And also we can answer the question, 'how significant are the predictors?' Here we show the same analysis for all three predictors.

**Question**: Which ones are important?



Before we answer this question, we need to answer another question.



- Linear models
- Estimate of the regression coefficients
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- Confidence intervals for the predictors estimates
- Bootstrap
- Evaluating Significance of Predictors
- How well we know the model  $\hat{f}$

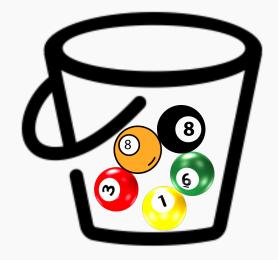


In the lack of active imagination, parallel universes and the likes, we need an alternative way of producing fake data set that resemble the parallel universes.

Bootstrapping is the practice of sampling from the observed data (X,Y) in estimating statistical properties.



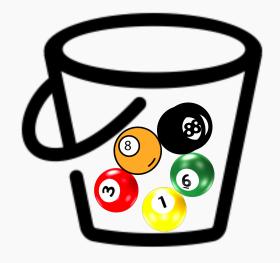
Imagine we have 5 billiard balls in a bucket.





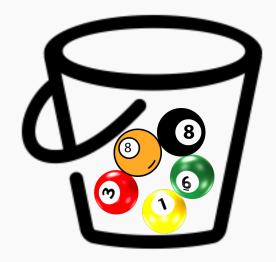


We first pick randomly a ball and replicate it. This is called **sampling** with replacement. We move the replicated ball to another bucket.





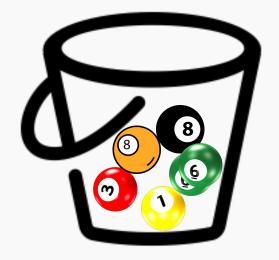






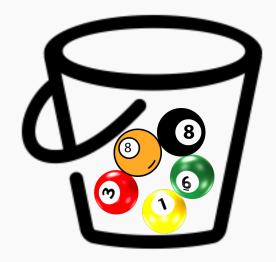


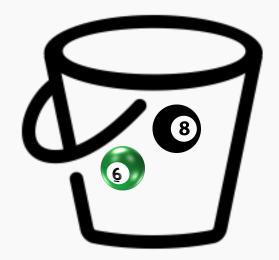
We then randomly pick another ball and again we replicate it. As before, we move the replicated ball to the other bucket.





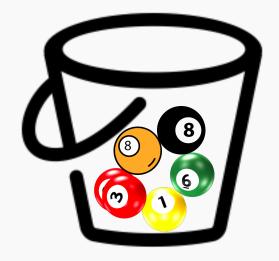


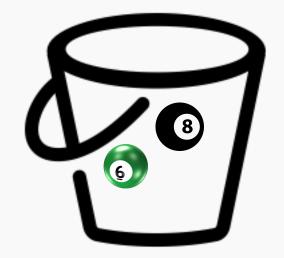






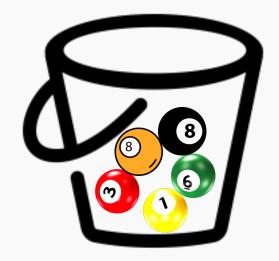
We repeat this process.

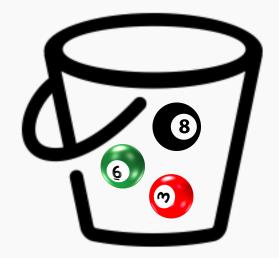






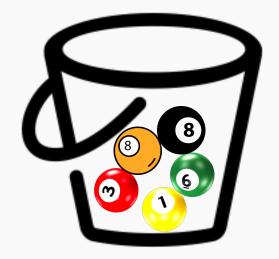
Again

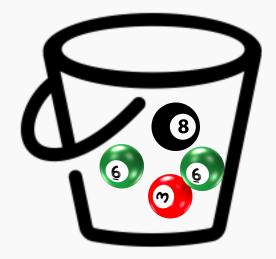






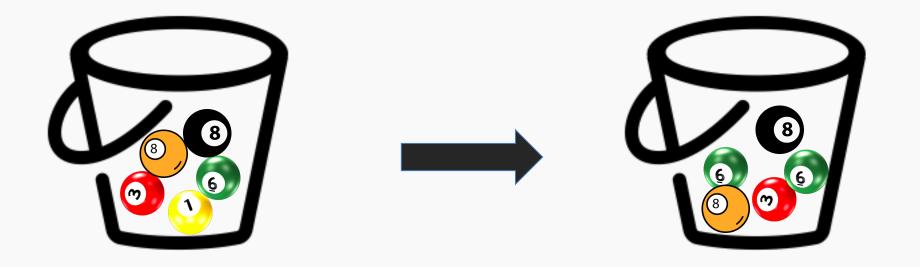
And again







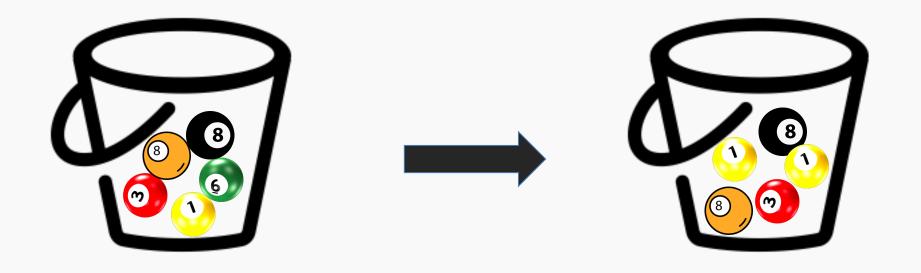
Until the "other" bucket has **the same number of balls** as the original one.



#### This new bucket represents a new parallel universe

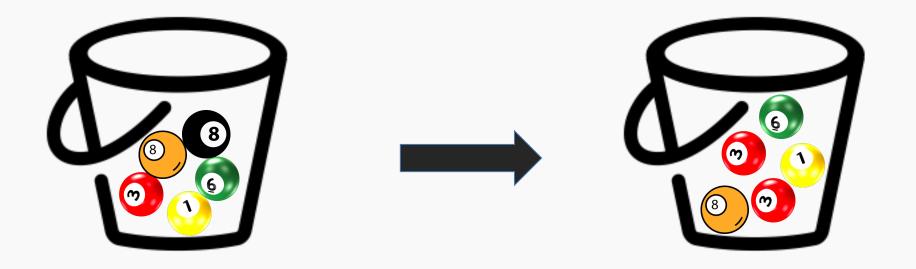


We repeat the same process and acquire another sample.





We repeat the same process and acquire another sample.



#### These new buckets represents the parallel universes



#### Definition

Bootstrapping is the practice of estimating properties of an estimator by measuring those properties by, for example, sampling from the observed data.

For example, we can compute  $\hat{\beta}_0$  and  $\hat{\beta}_1$  multiple times by randomly sampling from our data set. We then use the variance of our multiple estimates to approximate the true variance of  $\hat{\beta}_0$  and  $\hat{\beta}_1$ .



We can empirically estimate the **standard errors**,  $SE(\hat{\beta}_0)$ ,  $SE(\hat{\beta}_1)$  of  $\beta_0$  and  $\beta_1$  through bootstrapping.

If for each bootstrapped sample the estimated betas are:  $\hat{\beta}_{0,i}$ ,  $\hat{\beta}_{1,i}$ , then

$$SE(\hat{\beta}_{0}) = \sqrt{\operatorname{var}(\hat{\beta}_{0})}$$
$$SE(\hat{\beta}_{1}) = \sqrt{\operatorname{var}(\hat{\beta}_{1})}$$



#### Alternatively:

If we know the variance  $\sigma_{\epsilon}^2$  of the noise  $\epsilon$ , we can compute  $SE(\hat{\beta}_0), SE(\hat{\beta}_1)$  analytically using the formulae below (no need to bootstrap):

$$SE\left(\widehat{\beta}_{0}\right) = \sigma_{\epsilon}\sqrt{\frac{1}{n} + \frac{\overline{x}^{2}}{\sum_{i}\left(x_{i} - \overline{x}\right)^{2}}}$$
$$SE\left(\widehat{\beta}_{1}\right) = \frac{\sigma_{\epsilon}}{\sqrt{\sum_{i}\left(x_{i} - \overline{x}\right)^{2}}}$$



More data: 
$$n \uparrow$$
  
**Set**  $(\widehat{\mathbb{D}}_{\mathbb{Q}})_{x_{\overline{i}}} = \sigma_{\overline{x}} / \overset{1}{\xrightarrow{\sum}}_{n} \stackrel{\overline{x}^{2}}{\xrightarrow{\sum}}_{i} (x_{i} - \overline{x})^{2}$   
Larger coverage:  $var(x)$  or  $\sum_{i} (x_{i} - \overline{x})^{2} \uparrow \Longrightarrow SE \downarrow$   
**Better data:**  $\sigma^{2} \stackrel{1}{\xrightarrow{\sum}}_{i} \stackrel{1}{\xrightarrow{\sum}}_{i} (x_{i} - \overline{x})^{2}$ 

In practice, we do not know the theoretical value of  $\sigma$  since we do not know the exact distribution of the noise  $\epsilon$ .



However, if we make the following assumptions,

- the errors  $\epsilon_i = y_i \hat{y}_i$  and  $\epsilon_j = y_j \hat{y}_j$  are uncorrelated, for  $i \neq j$ ,
- each  $\epsilon_i$  has a mean 0 and variance  $\sigma_{\epsilon}^2$ ,

then, we can empirically estimate  $\sigma^2$ , from the data and our regression line:

$$\sigma_{\epsilon} \approx \sqrt{\frac{n \cdot \text{MSE}}{n-2}} = \sqrt{\frac{\sum_{i} (y_{i} - \hat{y}_{i})^{2}}{n-2}}$$

Remember:

$$y_i = f(x_i) + \epsilon_i \Longrightarrow \epsilon_i = y_i - f(x_i)$$



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More data: 
$$n \uparrow \text{and } \sum_{i} (x_i - \bar{x})^2 \uparrow \Longrightarrow SE \downarrow$$
  
Larger coverage:  $var(x)$  or  $\sum_{i} (x_i - \bar{x})^2 \uparrow \Longrightarrow SE \downarrow$   
Better data:  $\sigma^2 \downarrow \Rightarrow SE \downarrow$ 

$$SE\left(\widehat{\beta}_{0}\right) = \sigma \sqrt{\frac{1}{n} + \frac{\overline{x}^{2}}{\sum_{i} (x_{i} - \overline{x})^{2}}}$$
$$SE\left(\widehat{\beta}_{1}\right) = \frac{\sigma}{\sqrt{\sum_{i} (x_{i} - \overline{x})^{2}}}$$

**Better model:** 
$$(\hat{f} - y_i) \downarrow \Longrightarrow \sigma \downarrow \Longrightarrow SE \downarrow$$

$$\sigma \approx \sqrt{\sum \frac{(\hat{f}(x) - y_i)^2}{n - 2}}$$

**Question:** What happens to the  $\widehat{\beta_0}$ ,  $\widehat{\beta_1}$  under these scenarios?



#### The following results are for the coefficients for TV advertising:

Method	$SE(\hat{eta}_1)$
Analytic Formula	0.0061
Bootstrap	0.0061

The coefficients for TV advertising but restricting the coverage of x are:

Method	$SE(\hat{eta_1})$	
Analytic Formula	0.0068	
Bootstrap	0.0068	
		This makes no sense

#### The coefficients for TV advertising but with added **extra** noise:

Method	$SE(\hat{\beta}_1)$				
Analytic Formula	0.0028				
Bootstrap	0.0023				
CS109A, Protopapas, Rader, Tanner					



**Exercise:** Duplicate the following results for the coefficients for TV advertising.

Method	$SE(\hat{eta}_0)$	$SE(\hat{eta}_1)$
Analytic Formula	0.353	0.0028
Bootstrap	0.328	0.0023



- Linear models
- Estimate of the regression coefficients
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**Question:** What do you think a predictor coefficient means?

Sales = 7.5 + 0.04 TV

What does 7.5 mean and what does 0.04 mean?

If we increase the TV by \$1000, what would you expect the increase in sales to be?

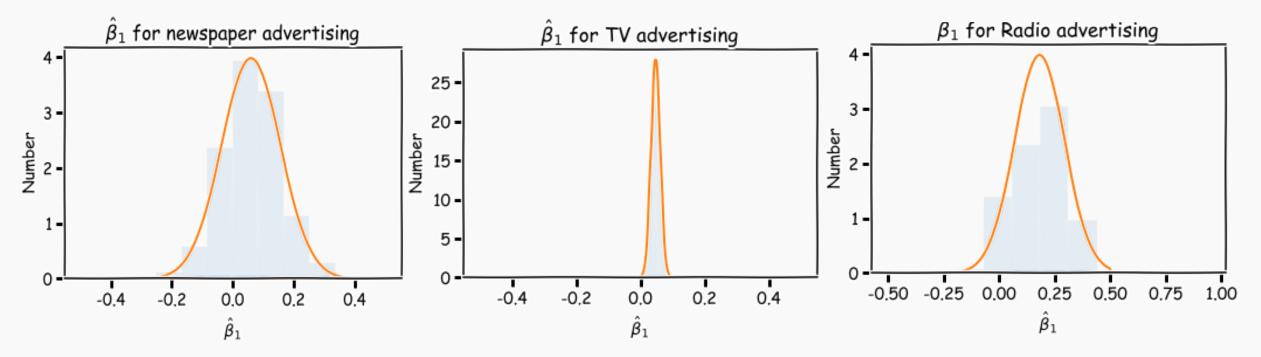
What if? Sales = 7.5 + 1.01 TV

**The interpretation of the predictors** depends on the values but decisions depend on how much we trust these values.



And also we can answer the question, 'how significant are the predictors?' Here we show the same analysis for all three predictors.

**Question**: Which ones are important?

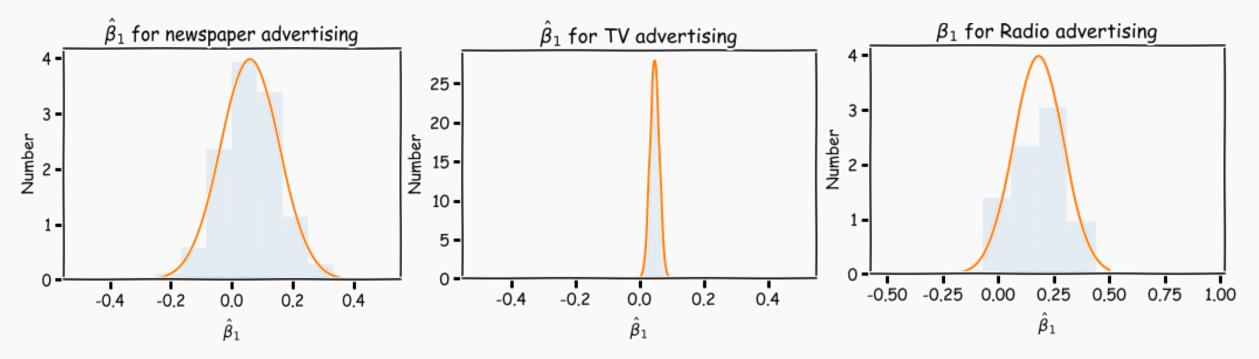


Before we answer this question, we need to answer another question.



And also we can answer the question, 'how significant are the predictors?' Here we show the same analysis for all three predictors.

**Question**: Which ones are important?



Now we know how to generate these distributions we are ready to answer **'how significant are the predictors?'** 



## Hypothesis Testing

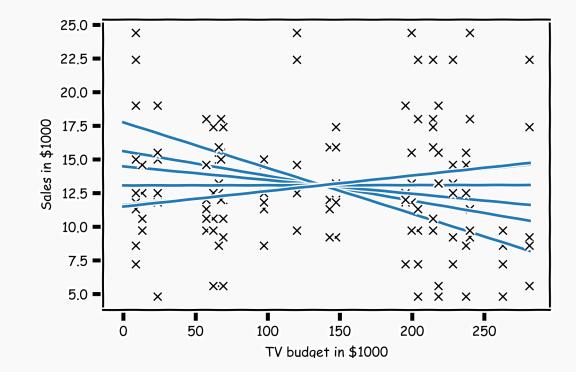
Hypothesis testing is a formal process through which we evaluate the validity of a statistical hypothesis by considering evidence **for** or **against** the hypothesis gathered by **random sampling of the data**.



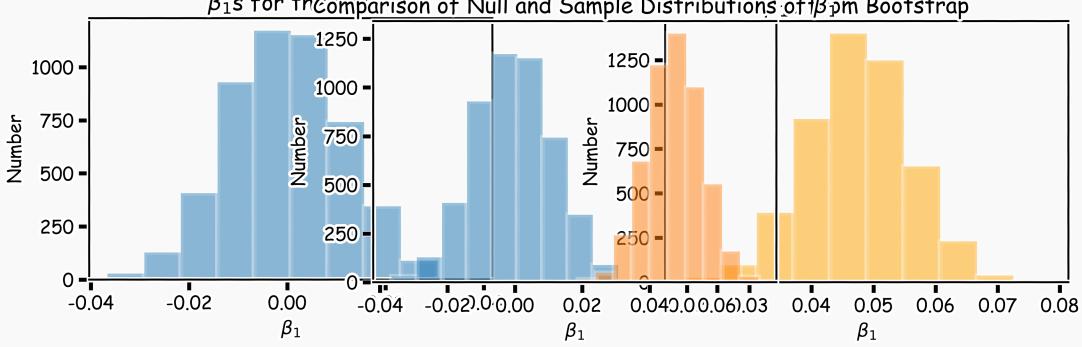
τν	sales
88694	22.1
29457	10.4
29428	9.3
<b>299</b> 8	18.5
<b>1868</b> 8	12.9
<b>296</b> 8	7.2
<b>8675</b> 4	11.8
29925	13.2
299.9	4.8
<b>793</b> 8	10.6
88922	8.6
20205	17.4
43999	9.2
<b>788</b> 9	9.7
298.2	19.0
29532	22.4
83588	12.5
2968	24.4

## Random sampling of the data

Shuffle the values of the predictor variable

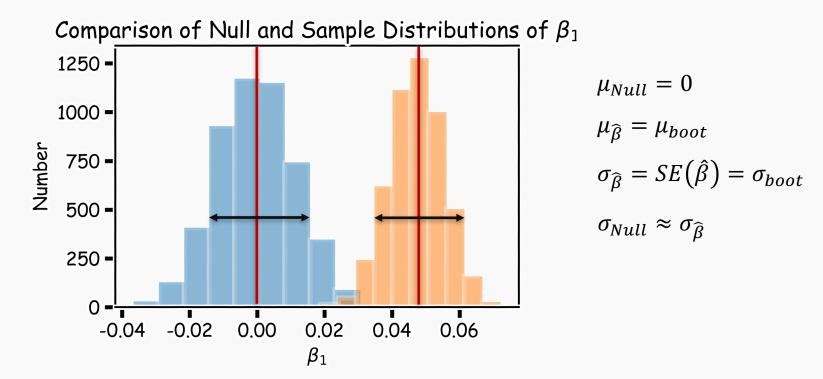






#### $\beta_1$ s for the omparison of Null and Sample Distributions of $\beta_p$ m Bootstrap





Translate this to the significance. Let's look at the distance of the estimated value of the coefficient in units of SE( $\hat{\beta}_1$ ) =  $\sigma_{\hat{\beta}_1}$ .

$$\mathsf{D} = \frac{\mu_{\widehat{\beta}} - \mu_{Null}}{\sqrt{\sigma_{Null}^2 + \sigma_{\widehat{\beta}}^2}} = \frac{\mu_{\widehat{\beta}}}{\sqrt{\sigma_{Null}^2 + \sigma_{\widehat{\beta}}^2}} = \frac{\mu_{\widehat{\beta}}}{\sqrt{2}\sigma_{\widehat{\beta}}}$$

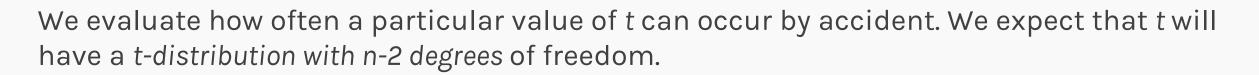


## Importance of predictors

In practice, we do not need the distribution for Null. Define a test statistic, which we we call t-test statistic

$$t = \frac{\mu_{\widehat{\beta}_1}}{\sigma_{\widehat{\beta}_1}}$$

Which measures the distance from zero in units of standard deviation.



To compute the probability of observing any value equal to |t| or larger, assuming  $\hat{\beta}_1 = 0$  is easy. We call this probability the **p-value**.

a small p-value (<0.05) indicates that it is unlikely to observe such a substantial association between the predictor and the response due to chance.

 $\mu_{\hat{\beta}_1} = 0$ 

 $\sigma_{\widehat{\beta}_1}$ 

μŝ

0.02

0.04

 $\hat{\beta}_1$ 

0.06

- 20 Jumper

10 -

0 -

0.00

 $2\sigma_{\hat{\beta}_1}$ 

0.08

0.10



## Hypothesis Testing

Hypothesis testing is a formal process through which we evaluate the validity of a statistical hypothesis by considering evidence for or against the hypothesis gathered by **random sampling** of the data.

- 1. State the hypotheses, typically a **null hypothesis**,  $H_0$  and an **alternative hypothesis**,  $H_1$ , that is the negation of the former.
- 2. Choose a type of analysis, i.e. how to use sample data to evaluate the null hypothesis. Typically this involves choosing a single test statistic.
- **3.** Sample data and compute the test statistic.
- 4. Use the value of the test statistic to either reject or not reject the null hypothesis.



### **1. State Hypothesis:**

## Null hypothesis:

 $H_0$ : There is no relation between X and Y

### The alternative:

 $H_a$ : There is some relation between X and Y

### 2: Choose test statistics

To test the null hypothesis, we need to determine whether, our estimate for  $\hat{\beta}_1$ , is sufficiently far from zero that we can be confident that  $\hat{\beta}_1$  is non-zero. We use the following test statistic:

$$t = \frac{\mu_{\widehat{\beta}_1}}{\sigma_{\widehat{\beta}_1}}$$
cs109A, Protopapas, Rader, Tanner



#### 3. Sample:

Using bootstrap we can estimate  $\hat{\beta}'_1$ s, and therefore  $\mu_{\hat{\beta}_1}$  and  $\sigma_{\hat{\beta}_1}$ .

### 4. Reject or not reject the hypothesis:

If there is really no relationship between X and Y, then we expect that will have a *t*-distribution with *n*-2 degrees of freedom.

To compute the probability of observing any value equal to |t| or larger, assuming  $\hat{\beta}_1 = 0$  is easy. We call this probability the p-value.

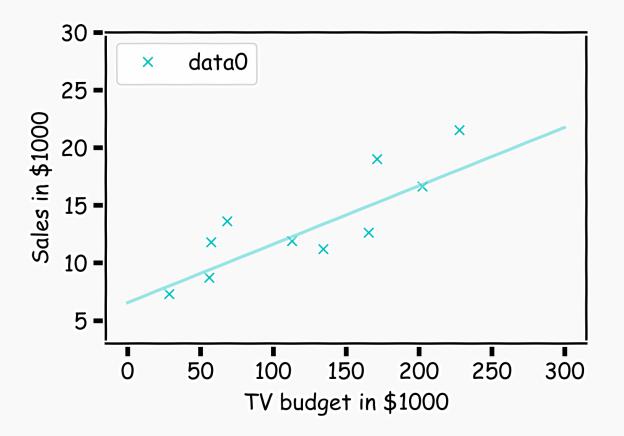
a small p-value indicates that it is unlikely to observe such a substantial association between the predictor and the response due to chance



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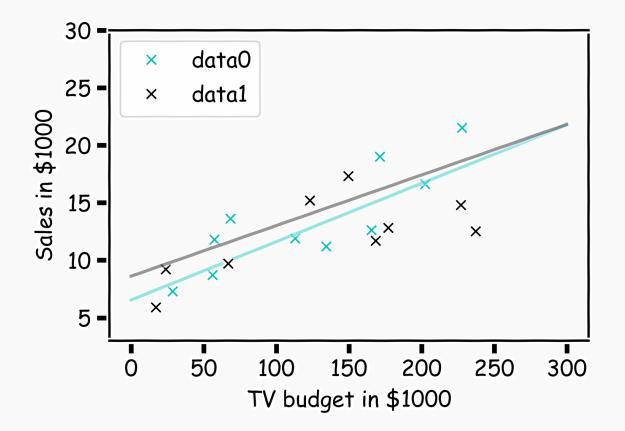


Our confidence in f is directly connected with the confidence in  $\beta$ s. So for each bootstrap sample, we have one  $\beta$  which we can use to determine the model.



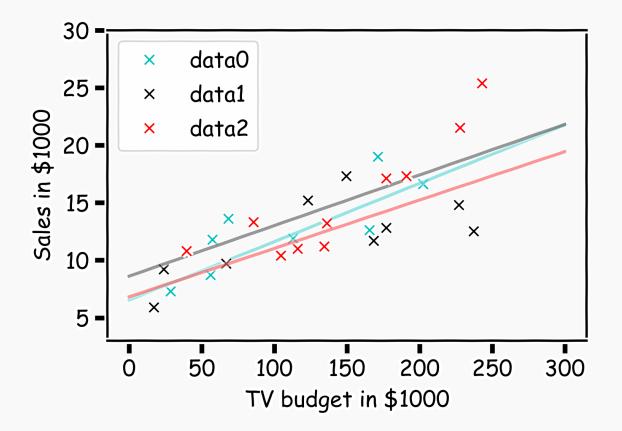


Here we show two difference set of models given the fitted coefficients.





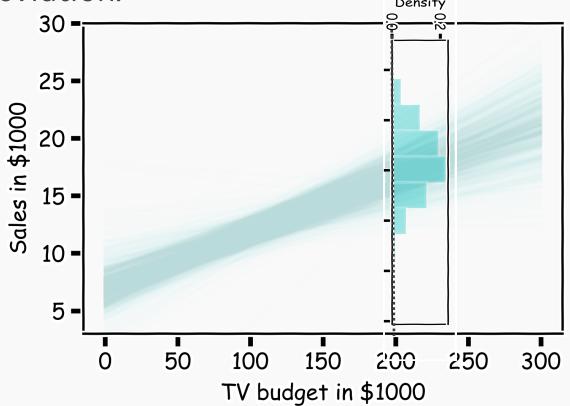
There is one such regression line for every bootstrapped sample.





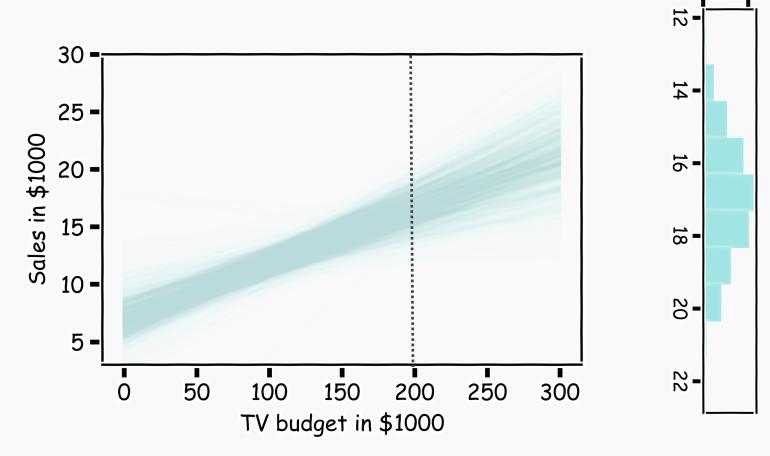
Below we show all regression lines for a thousand of such bootstrapped samples.

For a given x, we examine the distribution of  $\hat{f}$ , and determine the mean and standard deviation.



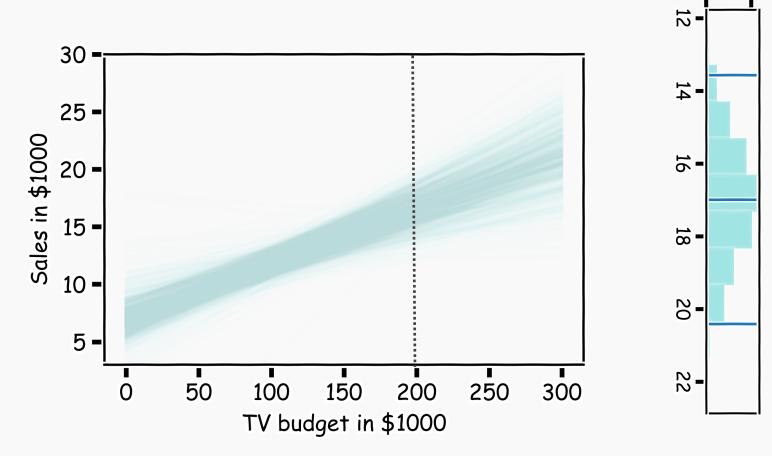


Below we show all regression lines for a thousand of such sub-samples. For a given x, we examine the distribution of  $\hat{f}$ , and determine the mean and standard deviation.



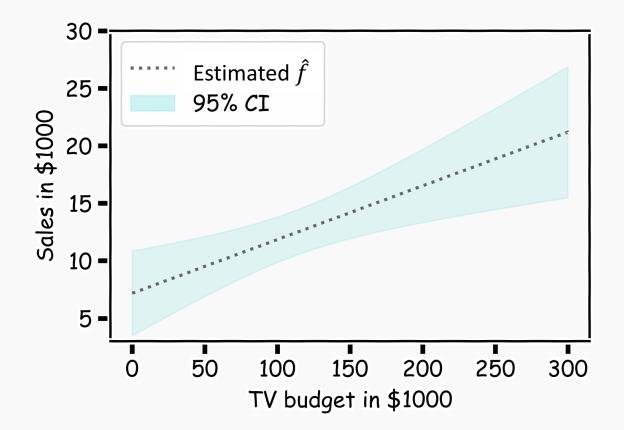


Below we show all regression lines for a thousand of such sub-samples. For a given x, we examine the distribution of  $\hat{f}$ , and determine the distribution of  $\hat{f}$ .



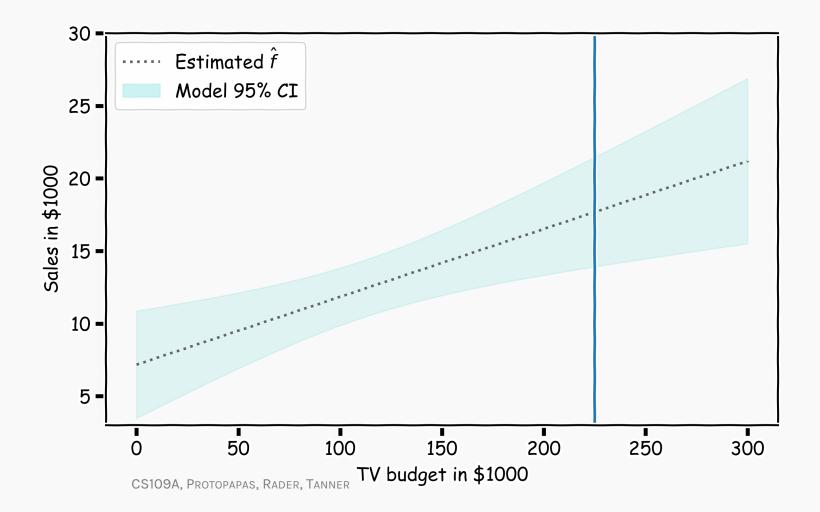


For every x, we calculate the mean of the models,  $\hat{f}$  (shown with dotted line) and the 95% CI of those models (shaded area).





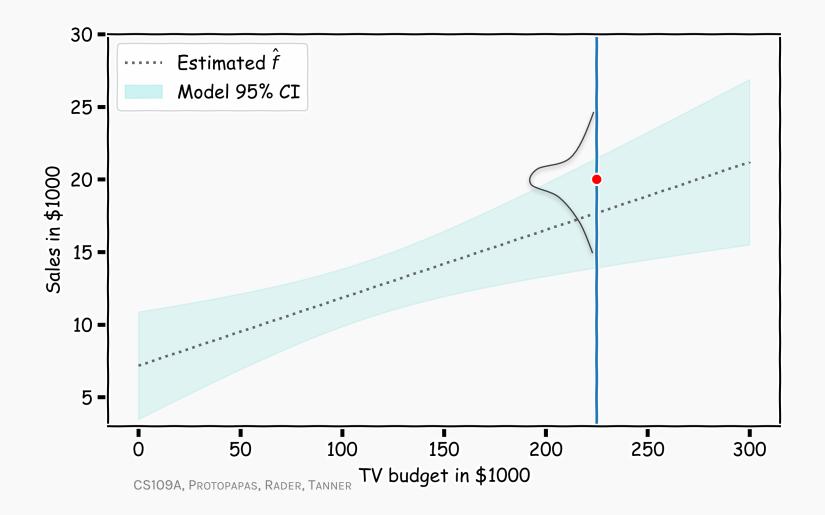
## Confidence in predicting $\hat{y}$





# Confidence in predicting $\hat{y}$

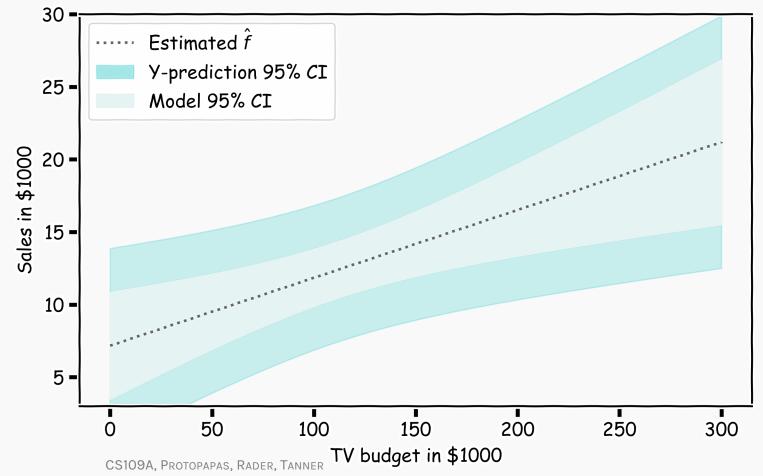
- for a given x, we have a distribution of models f(x)
- for each of these f(x), the prediction for  $y \sim N(f, \sigma_{\epsilon})$





# Confidence in predicting $\hat{y}$

- for a given x, we have a distribution of models f(x)
- for each of these f(x), the prediction for  $y \sim N(f, \sigma_{\epsilon})$
- The prediction confidence intervals are then





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#### **Model Fitness**

How does the model perform predicting?

#### **Comparison of Two Models**

How do we choose from two different models?

### **Evaluating Significance of Predictors**

Does the outcome depend on the predictors?

How well do we know  $\widehat{f}$ 

The confidence intervals of our  $\hat{f}$ 



### **Multiple predictors**

Collinearity Categorical variables

### **Polynomial regression**

Interaction terms



**Quiz** - to be completed in the next 10 min: Sway: Lecture 5: Linear Regression

**Programmatic** – to be completed by lab time tomorrow: Lessons: Lecture 5: Linear Regression – three (3) exercises

